Course code	Course Name	L-T-P-Credits	Year of Introduction
CS362	Computer Vision	3-0-0-3	2016

Pre-requisite: NIL

Course Objectives

- To build an understanding on detailed models of image formation.
- To expose the students to image feature detection and matching.
- To introduce fundamental algorithms for pattern recognition.
- To introduce various classification techniques.
- To expose the students to various structural pattern recognition and feature extraction techniques.

Syllabus

Image formation and Image model with Components of a vision system, Multiple images and the Geometry of multiple views, High level vision, Basics of pattern recognition, Linear discriminant based classifiers and tree classifiers, Unsupervised Methods, Recent Advances in Pattern Recognition.

Expected Outcome

The students will be able to

i. Appreciate the detailed models of image formation.
ii. Analyse the techniques for image feature detection and matching.
iii. Apply various algorithms for pattern recognition.
iv. Examine various clustering algorithms.
v. Analyze structural pattern recognition and feature extraction techniques.

Text Books:

1. Bernd Jahne and Horst HauBecker, Computer vision and Applications, Academic press, 2000.
2. David A. Forsyth & Jean Ponce, Computer vision – A Modern Approach, Prentice Hall, 2002.

References

1. C. M. Bishop, Pattern Recognition and Machine Learning, Springer, 2006.
2. R. O. Duda, P. E. Hart and D. G. Stork, Pattern Classification, John Wiley, 2001.
3. Richard Hartley and Andrew Zisserman, Multiple View Geometry in Computer Vision, Second Edition, Cambridge University Press, 2004.
4. S. Theodoridis and K. Koutroumbas, Pattern Recognition, 4th Ed., Academic Press, 2009.

COURSE PLAN

Module	Contents	Hours	End Sem. Exam Marks

I	Image formation and Image model- Components of a vision system- Cameras- camera model and camera calibration- Radiometry- Light in space- Light in surface - Sources, shadows and shading.	**06**	**15%**
II	Multiple images-The Geometry of multiple views- Stereopsis- Affine structure from motion- Elements of Affine Geometry Affine structure and motion from two images- Affine structure and motion from multiple images- From Affine to Euclidean images.	**07**	**15%**
FIRST INTERNAL EXAM			
III	High level vision- Geometric methods- Model based vision- Obtaining hypothesis by pose consistency, pose clustering and using Invariants, Verification.	**07**	**15%**
IV	Introduction to pattern and classification, supervised and unsupervised learning, Clustering Vs classification, Bayesian Decision Theory- Minimum error rate classification Classifiers, discriminant functions, decision surfaces- The normal density and discriminant-functions for the Normal density.	**07**	**15%**
SECOND INTERNAL EXAM			
V	**Linear discriminant based classifiers and tree classifiers** Linear discriminant function based classifiers- Perceptron- Minimum Mean Squared Error (MME) method, Support Vector machine, Decision Trees: CART, ID3.	**07**	**20%**
VI	**Unsupervised Methods** Basics of Clustering; similarity / dissimilarity measures; clustering criteria. Different distance functions and similarity measures, K-means algorithm. **Recent Advances in Pattern Recognition** Neural network structures for pattern recognition, Pattern classification using Genetic Algorithms.	**08**	**20%**
END SEMESTER EXAM			

Question Paper Pattern

1. There will be *five* parts in the question paper – A, B, C, D, E
2. Part A
   a. Total marks : 12
   b. *Four* questions each having *3* marks, uniformly covering modules I and II; All*four* questions have to be answered.
3. Part B
   a. Total marks : 18
   b. *Three*questions each having *9* marks, uniformly covering modules I and II;

T*wo* questions have to be answered. Each question can have a maximum of three subparts.

4. Part C
    a. Total marks : 12
    b. *Four* questions each having *3* marks, uniformly covering modules III and IV; All*four* questions have to be answered.
5. Part D
    a. Total marks : 18
    b. *Three*questions each having *9* marks, uniformly covering modules III and IV; *Two* questions have to be answered. Each question can have a maximum of three subparts
6. Part E
    a. Total Marks: 40
    b. *Six* questions each carrying 10 marks, uniformly covering modules V and VI; *four* questions have to be answered.
    c. A question can have a maximum of three sub-parts.

7. There should be at least 60% analytical/numerical questions.